

## Lecture 14: Basic Sampling

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## 1 What is Sampling?

In this section we address practical methods for generating samples and estimating properties of probability distributions. In most computers, we only have access to a *uniform* pseudo-random number generator  $U[0, 1]$ . We often wish to draw samples from some other distribution  $f(\cdot)$ : We would like to generate  $\mathbf{s}$  such that  $x_1, x_2, x_3, \dots, x_n \sim f$ . How can we do this?

Since we only have access to a uniform distribution, we need some way to transform samples or properties of the uniform distribution so that we get the distribution we want ( $f(\cdot)$ ). We will discuss three methods.

1. Inversion Method
2. Importance Sampling
3. Rejection Sampling

## 2 Inversion Method

The inversion method requires that we find the inverse of the cumulative distribution function (CDF) of  $f(\cdot)$ . Here we will use capital  $F(\cdot)$  to denote the CDF and lowercase  $f(\cdot)$  to denote the probability density function (PDF). To use the inversion method, we find the inverse function  $F^{-1}(\cdot)$  and apply  $F^{-1}(\cdot)$  to  $X \sim U[0, 1]$ . It should be noted that  $F(\cdot)$  is monotone increasing by the definition of the CDF. Therefore,  $F^{-1}(\cdot)$  exists. However,  $F^{-1}(\cdot)$  may not be easy to find - to use the inverse method one must be able to find or approximate  $F^{-1}(\cdot)$ .

The inversion method proceeds as follows:

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**Algorithm 1** Inversion Method

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Draw  $y_k \sim U[0, 1]$ ,  $k = 1, \dots, n$

Set  $x_k = F^{-1}(y_k)$

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To show that  $X \sim f$ , suppose we have a uniform random variable  $Y \sim U[0, 1]$ . Then we wish to show that  $F^{-1}(Y) \sim f$ . Note that this is true if and only if the CDFs are the same. That is, if  $P(F^{-1}(Y) \leq x) = F(x)$ . To prove this, start with

$$P(F^{-1}(Y) \leq x)$$

Now apply  $F(\cdot)$  to both sides of the inequality. Since  $F(\cdot)$  is monotone, the inequality is still valid. Since  $F(\cdot)$  is increasing, the direction (sign) of the inequality does not change.

$$P(F(F^{-1}(Y)) \leq F(x))$$

$F(F^{-1}(Y)) = Y$ , so we have that

$$P(Y \leq F(x))$$

$Y$  is uniformly distributed, and so  $P(Y \leq F(x)) = F(x)$  by the cumulative distribution of the uniform distribution. Therefore we have

$$P(F^{-1}(Y) \leq x) = F(x)$$

as desired.

### 3 Importance Sampling

Importance sampling is a way to estimate the properties (but not obtain samples) of  $f$  when we only have access to  $U[0, 1]$ . In importance sampling we consider the integral

$$I = \int w(x)f(x)dx$$

where  $w(x)$  is some function. Suppose we wish to estimate the mean of  $f(x)$ , but we do not have access to  $f(x)$  - instead we have access to  $g(x)$ . In our discussion here,  $g(x)$  is the standard uniform PDF. We can multiply the integrand by  $1 = g(x)/g(x)$  and obtain

$$I = \int \frac{w(x)f(x)}{g(x)}g(x)dx$$

which we recognize as the expectation of  $\frac{w(x)f(x)}{g(x)}$ :

$$I = \mathbb{E}_g \left[ \frac{w(x)f(x)}{g(x)} \right]$$

To actually estimate this expectation, compute an estimator  $\hat{I}$  of  $I$ , for  $x_1, x_2, \dots, x_N \sim g$ ,

$$\hat{I} = \frac{1}{N} \sum_{i=1}^N w(x_i) \frac{f(x_i)}{g(x_i)}$$

Or, put more succinctly,

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#### Algorithm 2 Importance Sampling

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Draw  $x_k \sim g$ ,  $k = 1, \dots, n$   
 Report  $\hat{I} = \frac{1}{n} \sum_{k=1}^n \frac{f(x_k)}{g(x_k)} w(x_k)$

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Here,  $\frac{f(x_k)}{g(x_k)}$  is called importance weight. It is easy to see that  $\hat{I}$  is an unbiased estimator. Since we want a good estimate of  $I$ , we are also interested in the variance. The variance of  $\hat{I}$  is

$$\text{Var}(\hat{I}) = \frac{1}{n} \left[ \int_0^1 \frac{w^2(x)f^2(x)}{g(x)} dx - I^2 \right]$$

Using the Cauchy-Schwarz inequality

$$\int_0^1 \frac{w^2(x)f^2(x)}{g(x)} dx = \int_0^1 \frac{w^2(x)f^2(x)}{g(x)} dx \cdot \int_0^1 g(x) dx \geq I^2$$

It should be noted that  $g$  cannot be arbitrary chosen - some choices for  $g$  will not work. In general the support of  $g$  must cover that of  $f$  and  $g$  must have a heavier tail than  $f$ .

To reduce the variance of  $\hat{I}$ , by the equality condition of Cauchy-Schwarz inequality, we need the curve  $\frac{w^2(x)f^2(x)}{g(x)}$  and  $g(x)$  to be as “well-aligned” as possible. That is, we require that the proportion between  $\frac{w^2(x)f^2(x)}{g(x)}$  and  $g(x)$  be nearly constant.

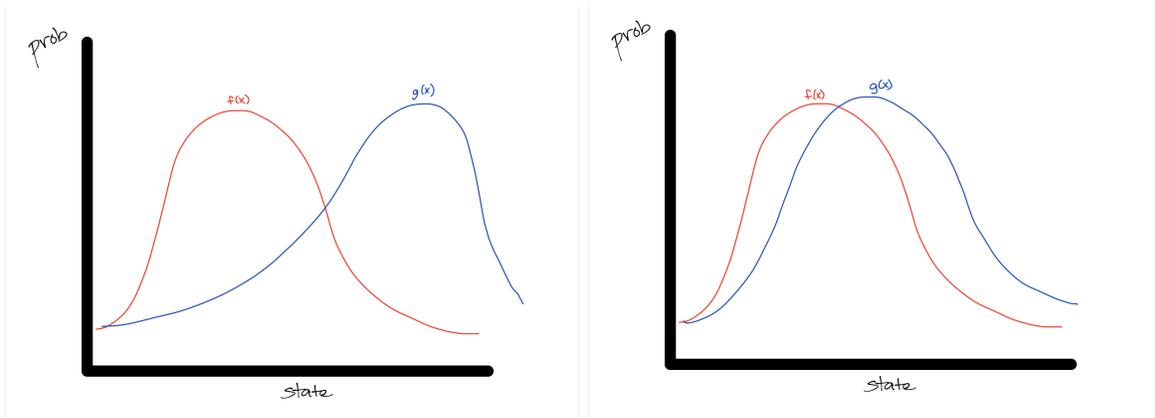


Figure 1: Choice of  $g$  given  $f$  for importance sampling. For low-variance estimates, we need a  $g$  that is similar to  $f$ . The plot on the left shows a bad choice for  $g$ , while the plot on the right shows a good choice.

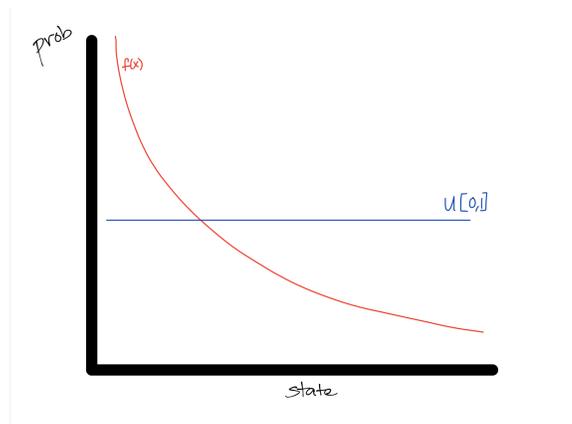


Figure 2: A situation where a uniform  $g(x)$  is not the best choice. In general, one should try to match the shape of  $g(x)$  to  $f(x)$  as far as is possible

**Why do we need importance sampling?** In general, we know that  $\int w(x)f(x)dx = E[w(x)]$  when sampling over the distribution  $f(x)$ . It is trivial to come up with an estimator for this quantity without using importance sampling when we can sample from  $f(x)$ . We do this by simply drawing  $x_1, x_2, \dots, x_n \sim f(x)$  and reporting  $\frac{1}{n} \sum_i w(x_i)$ . However it is not always possible (or efficient) to sample from  $f(x)$ . In this case, we use importance sampling to sample from  $g(x)$  and push the dependence on  $f$  into the importance weight.

## 4 Monte Carlo Estimation

Monte Carlo estimation is a special case of importance sampling, when we use the uniform distribution for  $g(x)$ . Suppose we wish to evaluate an integral with no closed-form solution, such as

$$I = \int_0^1 e^{-x^3} dx$$

We can use importance sampling to solve this problem. Let  $g(x) = f(x) = 1$  on the interval  $[0, 1]$  - that is,  $g, f = U[0, 1]$ . Now let  $w(u) = e^{-u^3}$ , where  $u \sim U[0, 1]$ , and note that

$$I = \mathbb{E}_u[e^{-u^3}]$$

Using our result from importance sampling, we may estimate  $I$  using  $\hat{I}$ .

$$\hat{I} = \frac{1}{N} \sum_{i=1}^N e^{-u_i^3}$$

where  $u_1, u_2, \dots, u_N \sim U[0, 1]$ .

## 5 Rejection Sampling

Importance sampling and Monte Carlo estimation were able to find the values of integrals involving  $f$ , but were not able to return actual samples from  $f$ . In this section we provide a method to generate actual samples from  $f(x)$ . Our goal is to sample from some complex distribution  $f$ , where  $f$  is the PDF of a random variable  $X$ . We know how to compute  $f(x)$  for every  $x$ , but we are given a sampler for another PDF,  $g(x)$ . Additionally, we know that there is some value  $M$  such that  $f(x) \leq Mg(x), \forall x$ . Rejection sampling works as follows.

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### Algorithm 3 Rejection Sampling

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Draw  $x \sim g$ 
Draw  $u \sim U[0, 1]$ 
if  $u \leq \frac{f(x)}{M \cdot g(x)}$  then
  Accept  $x$ 
else
  Loop
end if

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**Optimizing rejection sampling** This procedure guarantees that every sample that you generate will be from the distribution  $f(x)$ , but  $g(x)$  and  $M$  must be carefully chosen. Otherwise, a large portion of  $x$  will be rejected and the sampling procedure will be extremely slow. To make the sampling procedure fast, we want the following items:

1. Minimize  $M$ . We want to pick the smallest possible  $M$  such that  $\forall x, f(x) \leq M * g(x)$ . A smaller  $M$  implies a higher probability of accepting samples, which will mean that the algorithm will take less time to collect samples.
2. Choose a  $g(x)$  that is similar to  $f(x)$ . Choosing a good  $g(x)$  will result in choosing a smaller  $M$ .

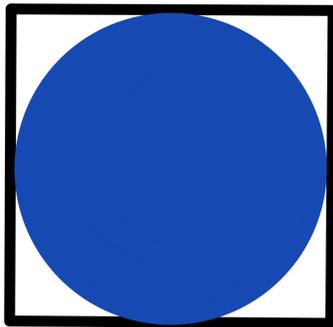


Figure 3: Dart throwing example of rejection sampling. First, we randomly generate points within the square. Then, we accept the points within the circle and reject the points outside the circle. Increasing  $M$  is equivalent to increasing the size of the square (fewer randomly sampled points will overlap with the circle).