

Cross-Domain Fault Localization: A Case for a Graph Digest Approach

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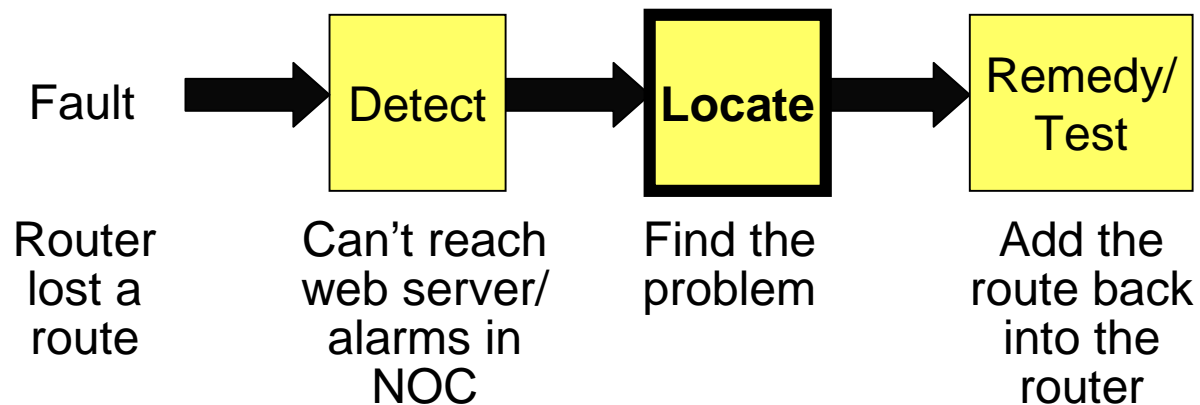
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Network Fault Localization

Fault localization: integral part of network management/troubleshooting



Not always easy to locate a fault

- Large number of devices
- Stale topology databases
- Human-introduced errors tough to find

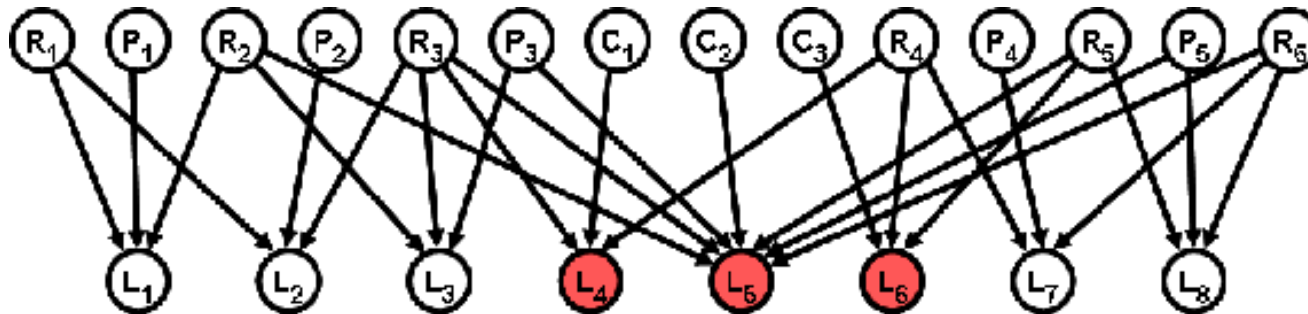
Cross-Domain Fault Localization

Networks are highly connected

- Some faults can affect many domains
 - E.g. DNS failure, link congestion
- **Correlating observations across domains intuitively increases accuracy of locating these types of faults**

Domains can represent fault propagation with a graph

- Common Ground



Challenges and Assumption

Challenges

- Domain managers are reluctant to share internal information
 - Topology, state, sensitive properties, etc
 - May even view other domains as *adversaries*
- Accuracy versus Privacy: competing goals
- Scalability: measured by the size of the aggregated inference graph

Assumption

- Domain managers will want to participate if
 - Privacy preserved
 - Fault localization accuracy improved

Related Work

Intra-domain: Significant recent advances in fault localization

- SHRINK [Kandula et al., 2005] and SCORE [Kompella et al., 2005]
 - bipartite causal graph model
- Sherlock [Bahl et al., 2007]
 - Multi-level causal graph model

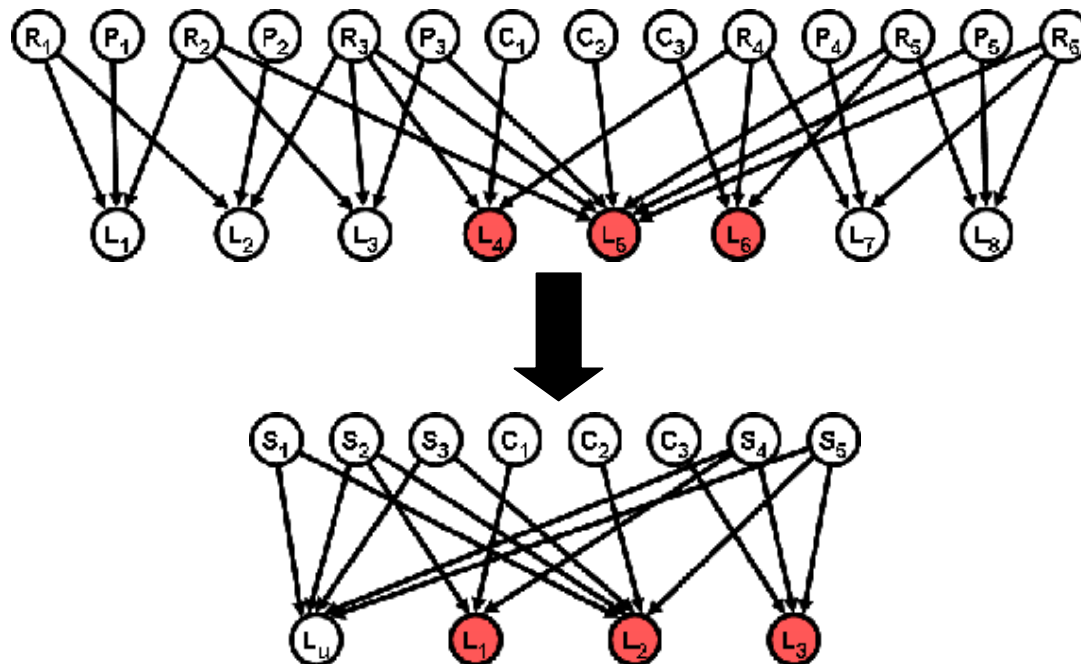
Cross-domain: under-researched

- End-to-end approach for hierarchical organizations [Steinder et al., 2008]
 - Constrained environment

Our Graph Digest Approach

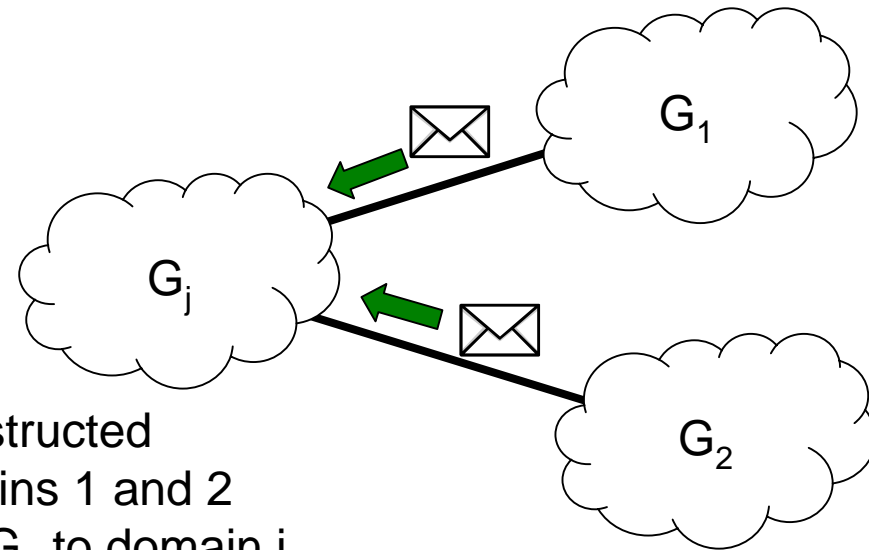
What is a graph digest?

A reduction of a fault propagation model (eg causal graph) to a digest representation of nodes and edges



Our Graph Digest Approach

$$G_j = \left(\bigcup_{i \neq j}^n f(G_i) \right) \cup G_j$$



1. Fault detected in j^{th} domain, G_j constructed
2. Domain j asks for digest from domains 1 and 2
3. Domains 1 and 2 send digests G_1, G_2 to domain j
4. Domain j imports the digests and runs inference

A general framework for creating and using a digest that explicitly models the inference accuracy and privacy requirements

Performance Criteria

Heart of the approach is quantifiable metrics for accuracy and privacy

Accuracy

$$h = \frac{|B_d \cap B_u|}{|B_d|} \quad c = \frac{|B_d \cap B_u|}{|B_u|}$$

B_u : Best explanation using undigested graphs

B_d : Best explanation using 1 undigested graph, 1+ digests

$$\alpha = \frac{2 * h * c}{h + c} \text{ for } h + c > 0, \text{ otherwise } \alpha = 0$$

Privacy: let S model adversary's knowledge of sensitive property

$$KL((S | digest), S) = \sum_{x \in X} \Pr(S = x | digest) \log_2 \frac{\Pr(S = x | digest)}{\Pr(S = x)}$$

Practical Privacy Metrics

KL Distance an ideal metric for a privacy criterion, but hard to quantify

In this work we look at protecting a domain against causal graph attacks

From causal graphs, can infer

- In-degree, out-degree, path lengths, reachability, etc

Sample privacy metrics:

- Reachability, number of routers, maximum node degree, diameter

Illustration SHRINK

Assumptions

- Bipartite model
- Independent SRG failures
- No more than 3 simultaneous failures

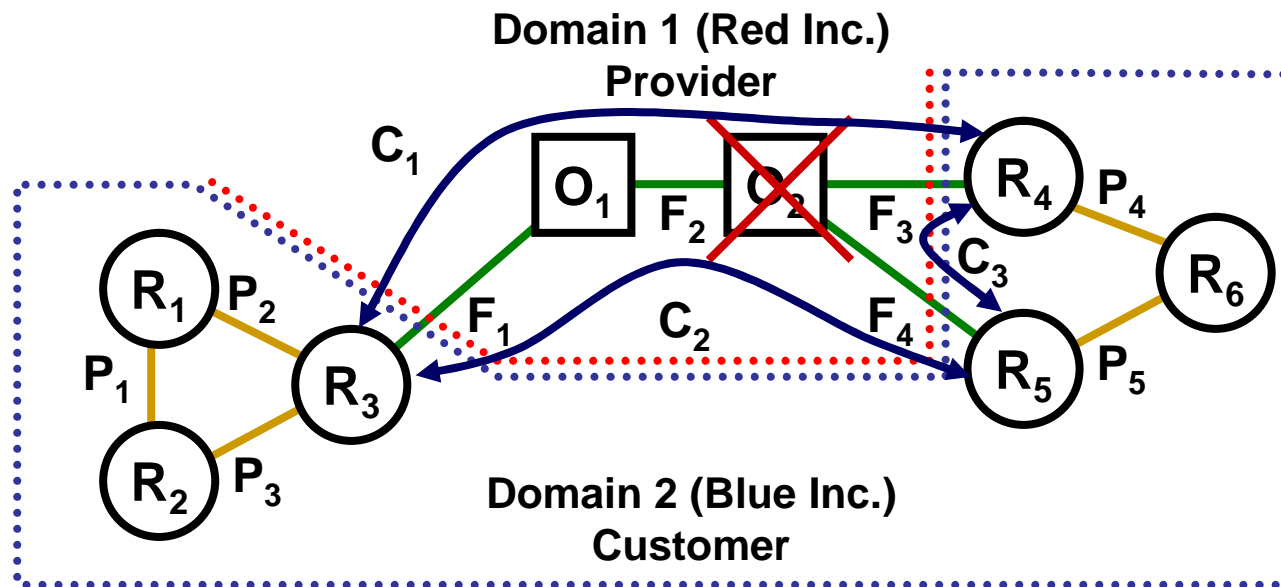
$$\arg \max_{\langle S_1, \dots, S_n \rangle} \Pr(\langle S_1, \dots, S_n \rangle \mid \langle L_1, \dots, L_m \rangle)$$

Adds “noisy” edges to form complete bipartite graph

- $d = .0001$ edge strength for a noisy edge $\Pr(L_j \mid S_i) = .0001$
- Subtract d from any edge strength of 1.0 $\Pr(L_j \mid S_i) = .9999$

Returns most probable explanation for the observations

Illustration SHRINK



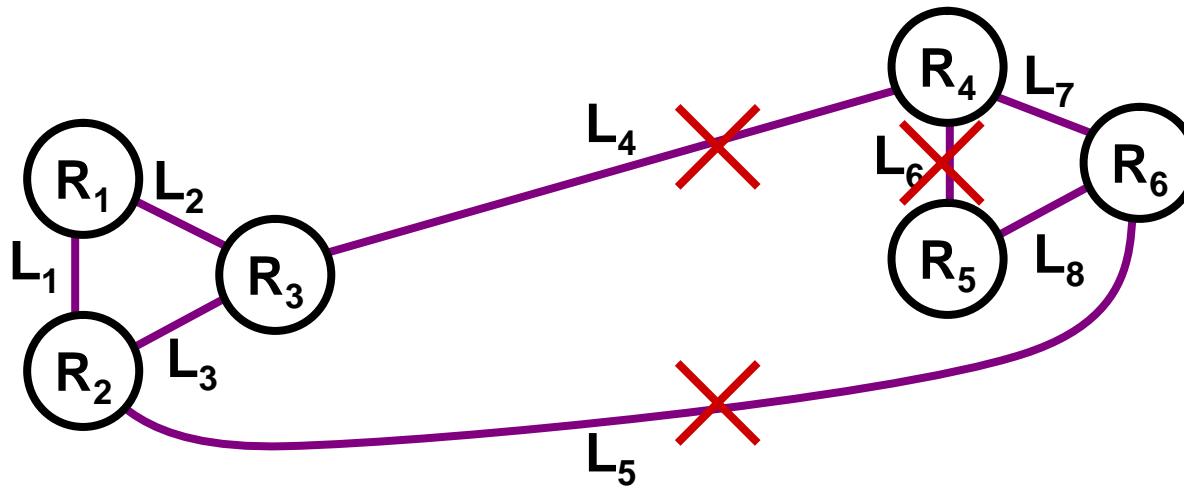
Identifiers:

- R* IP Router
- P* Point to Point link
- C* Leased Optical Circuit
- F* Optical Fiber
- O* Optical Switch



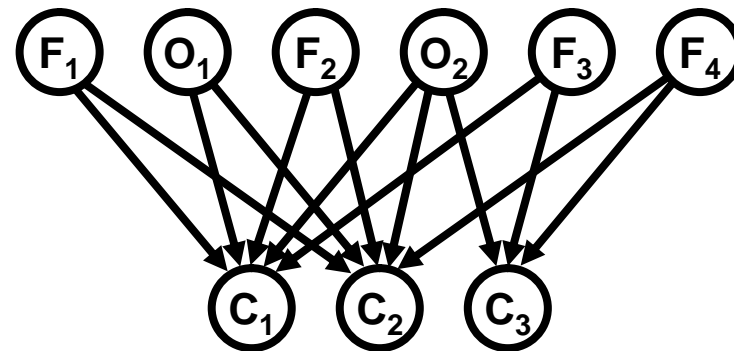
Topology

Illustration SHRINK



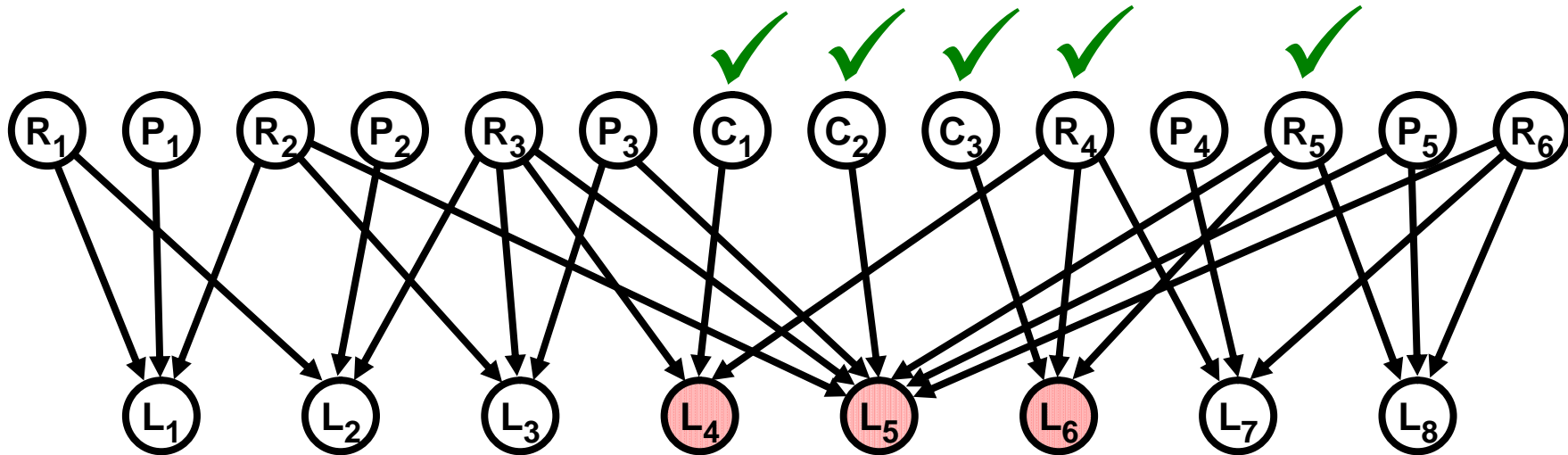
IP View

Illustration SHRINK



Provider Causal Graph
(with respect to customer)

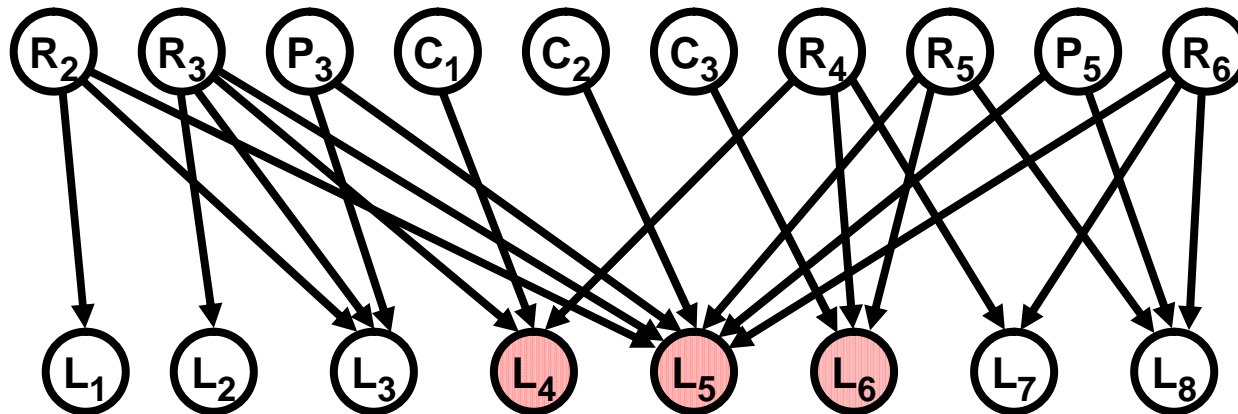
Illustration SHRINK



Best explanation

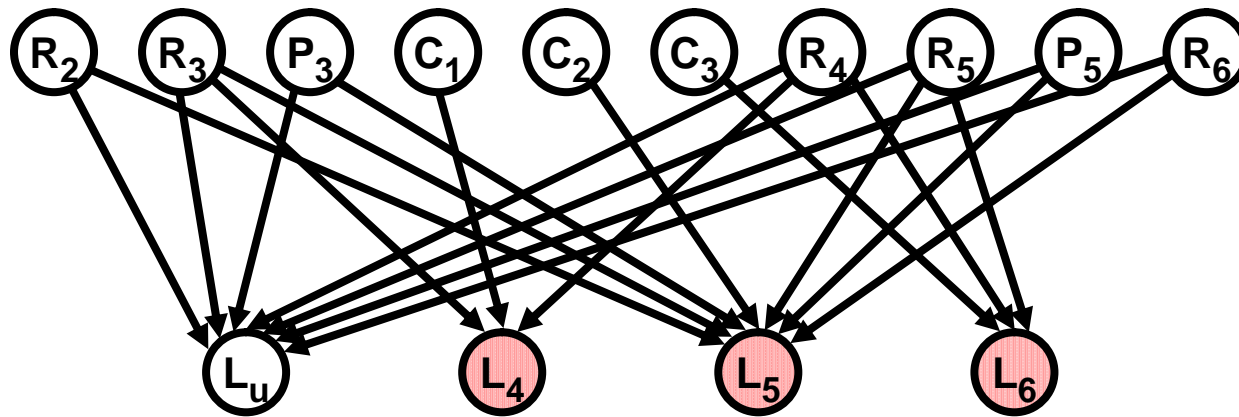
Customer Causal Graph
with observation state

Illustration SHRINK



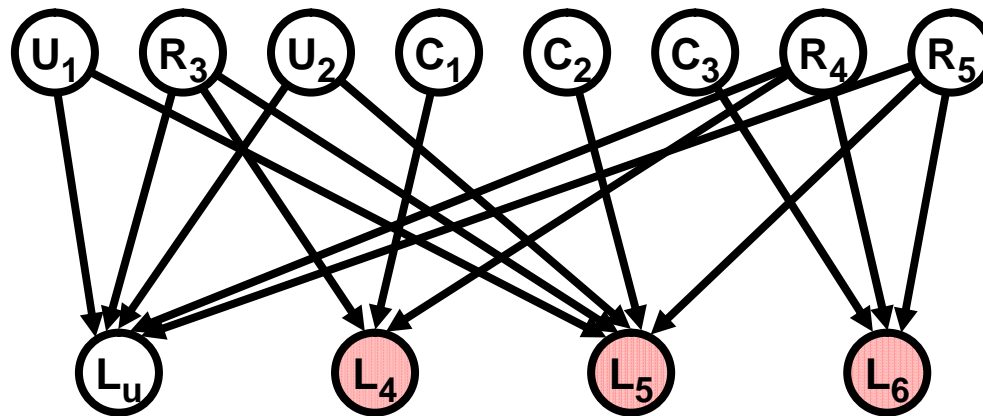
Nodes R₁, P₁, P₂, P₄ pruned

Illustration SHRINK



Combing all “up” observations

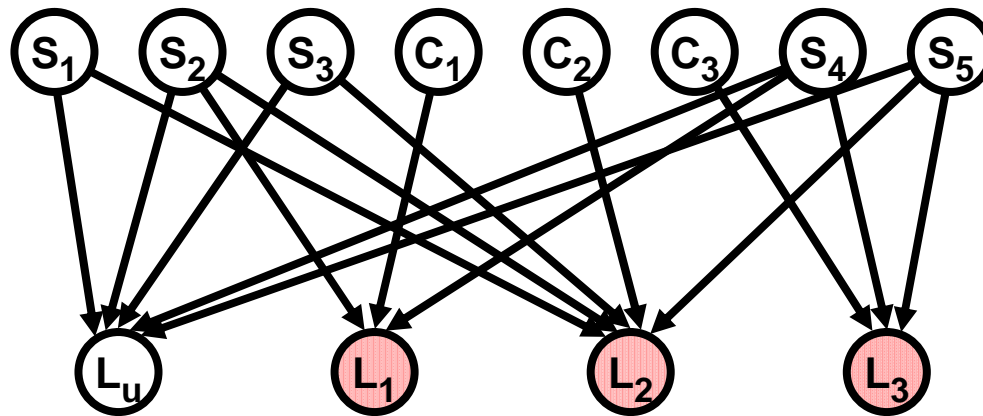
Illustration SHRINK



U1 = R2,R6
U2 = P3,P5

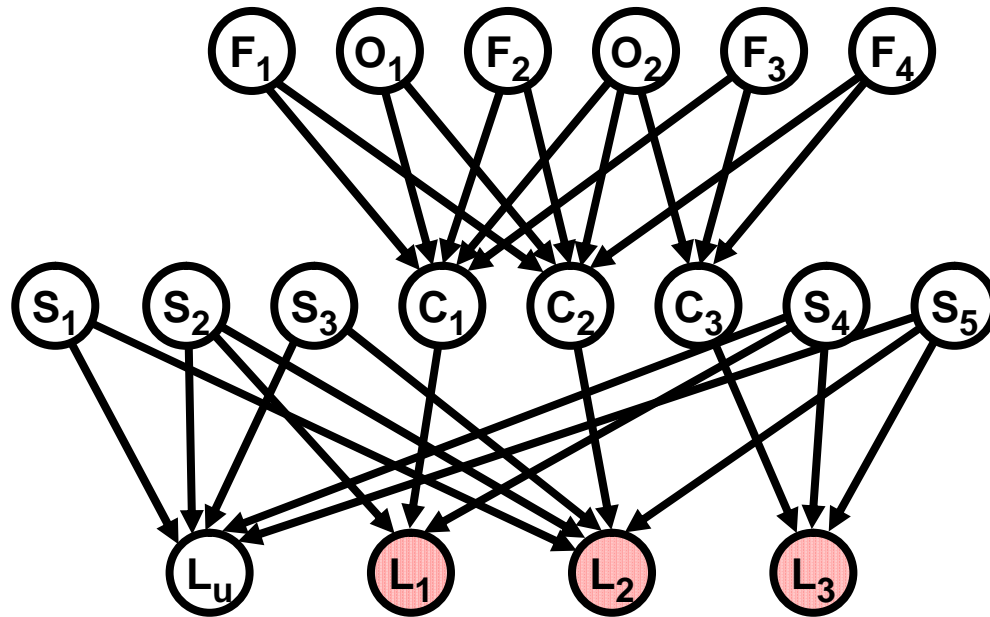
Aggregating nodes that are
indistinguishable in the causal graph

Illustration SHRINK



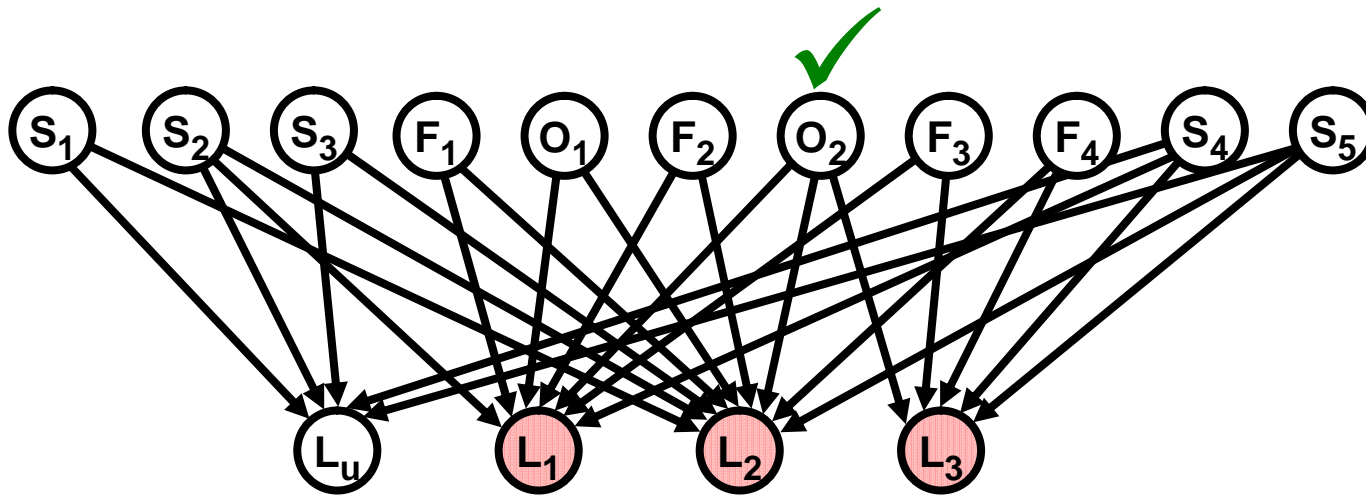
Renaming all but the “shared attribute” nodes and L_u

Illustration SHRINK



Multilevel union

Illustration SHRINK



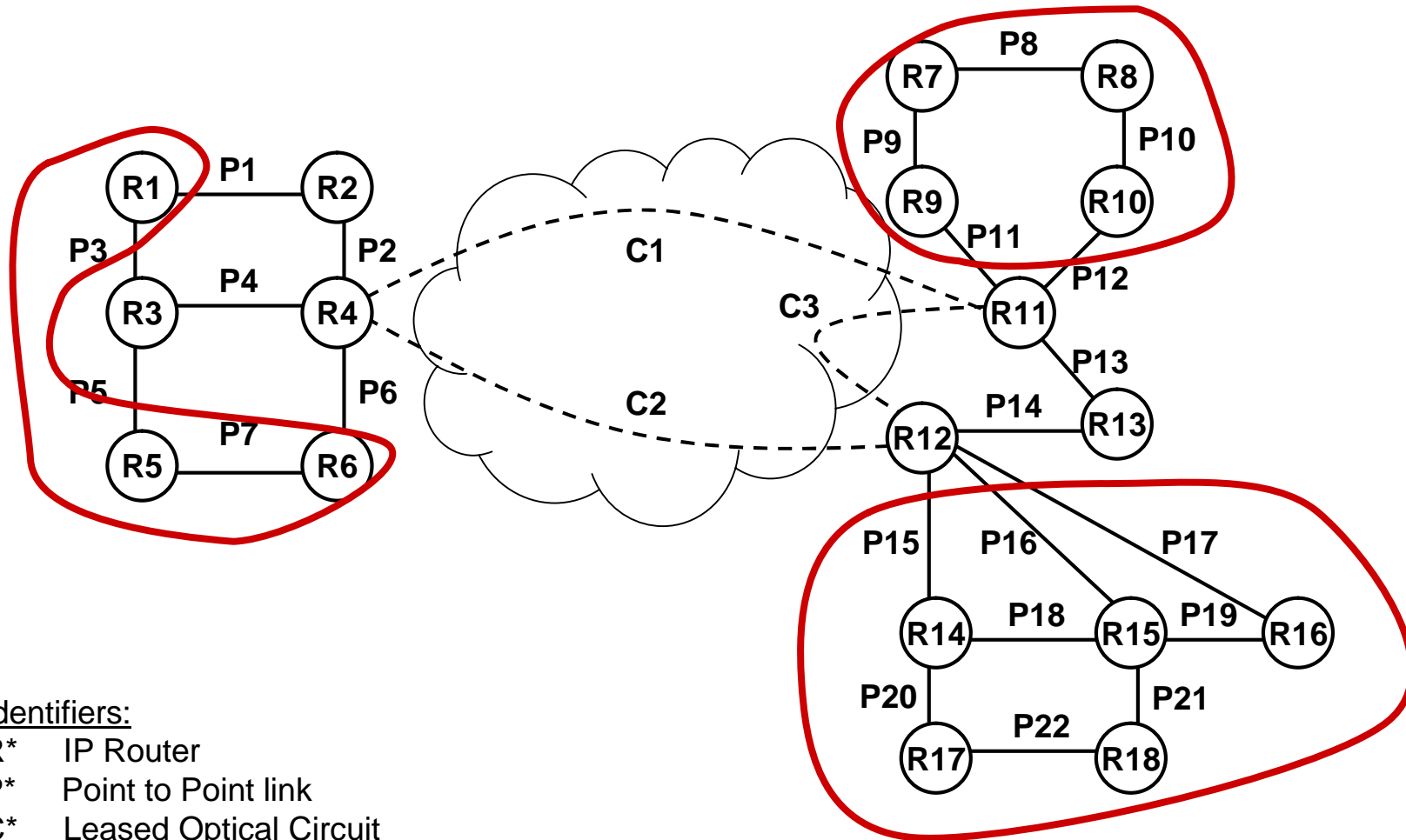
Model Specific Bipartite Union



Best explanation

Continuing Work

Customer Network Physical Topology



Identifiers:

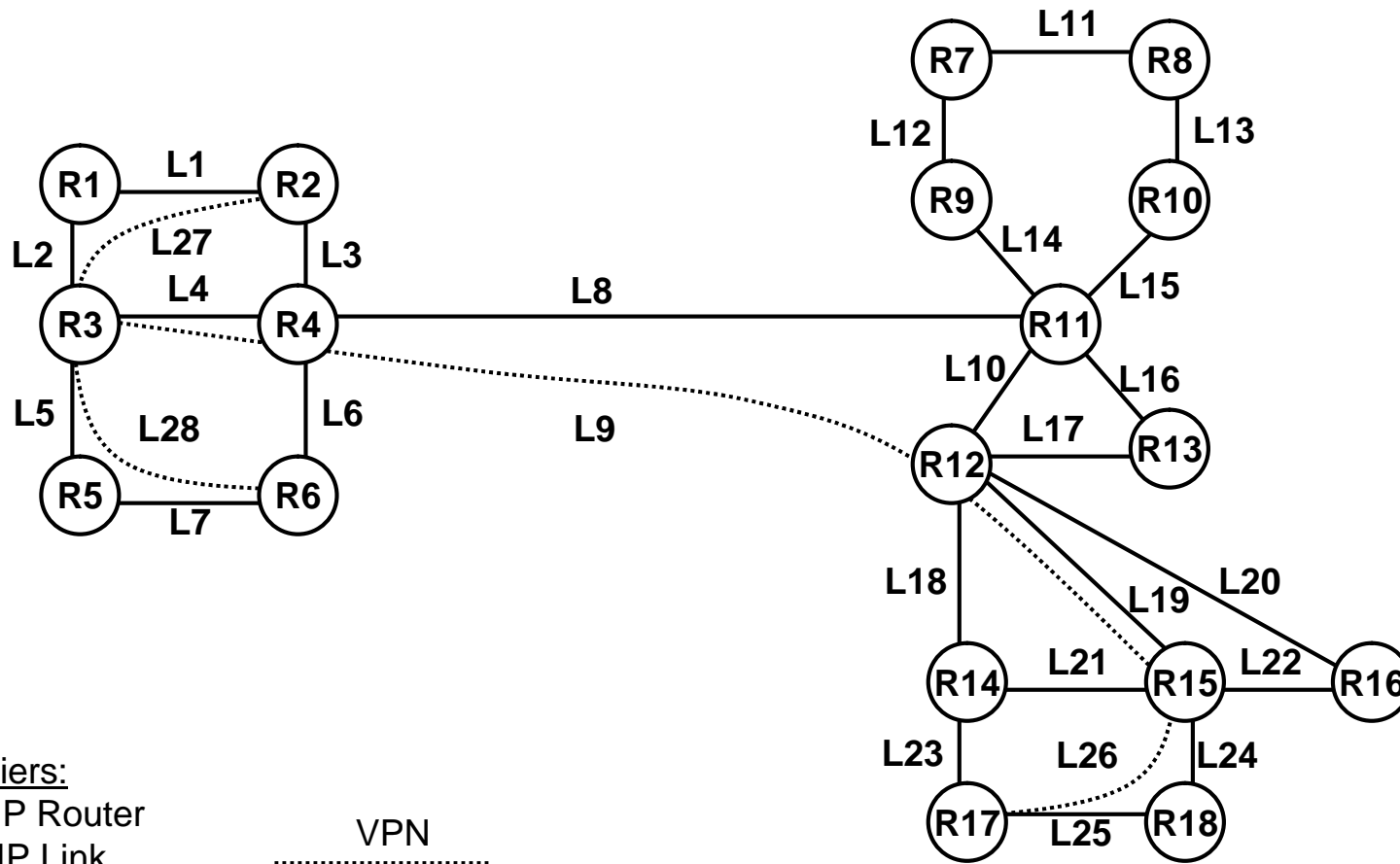
R* IP Router

P* Point to Point link

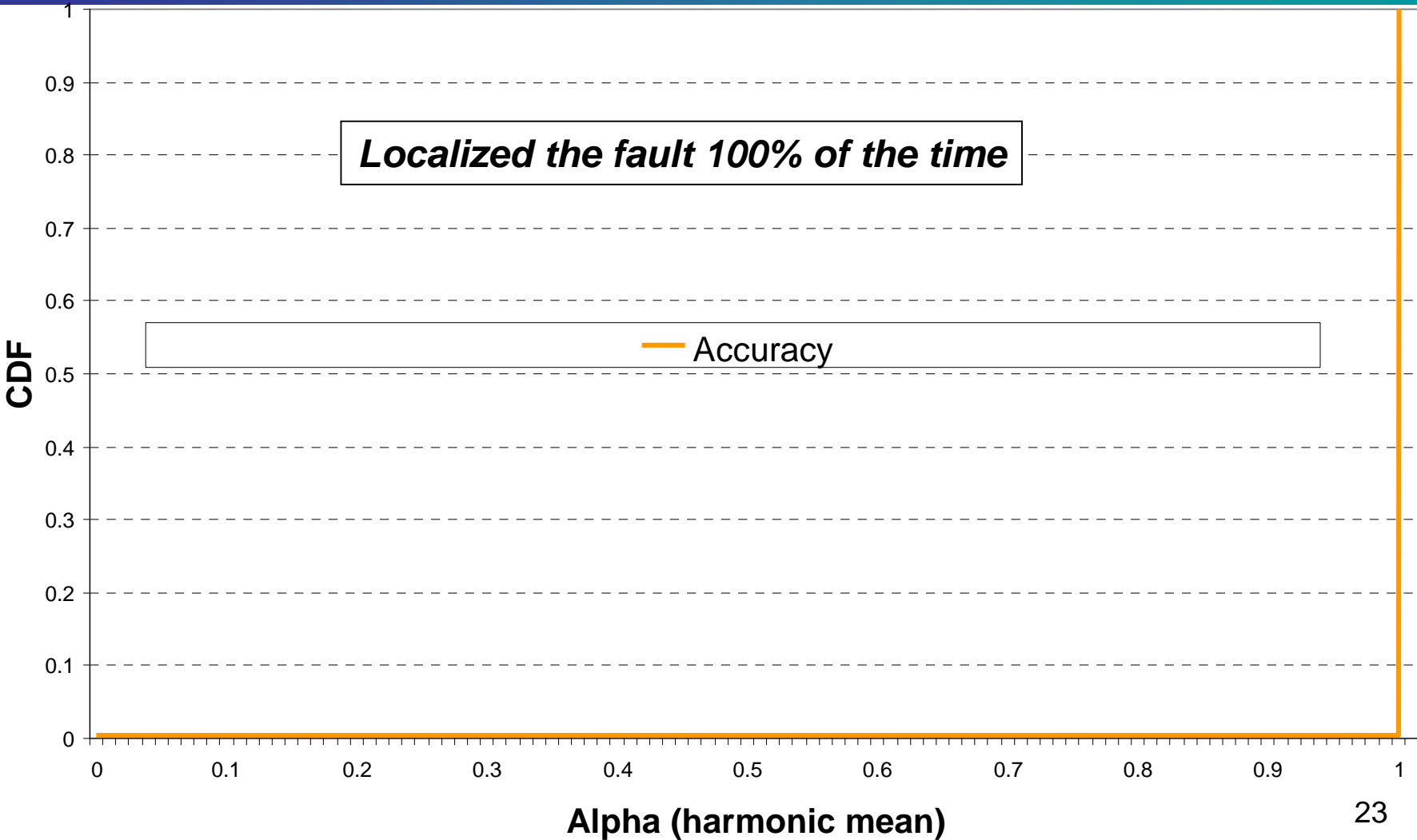
C* Leased Optical Circuit

Continuing Work

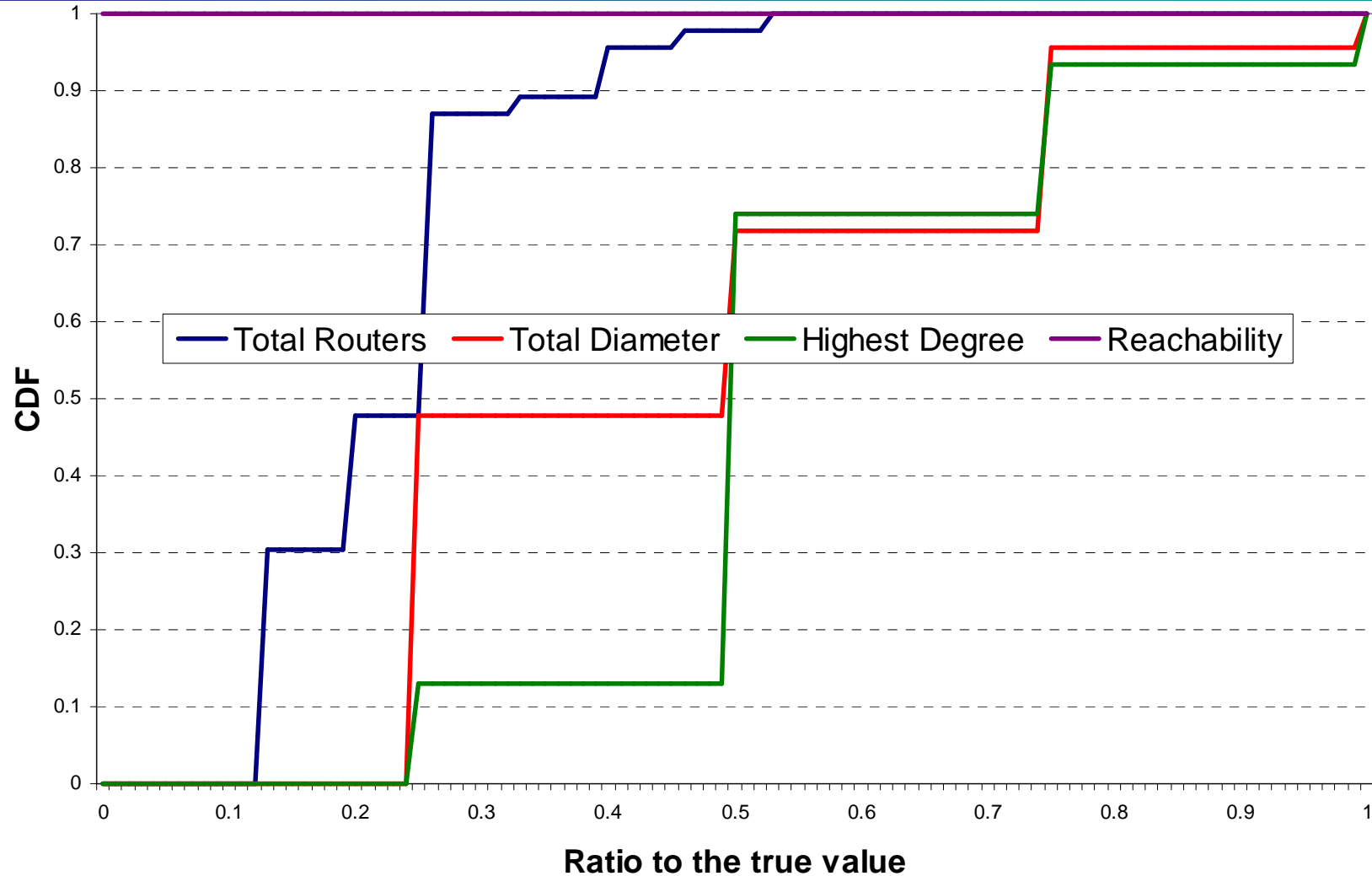
Customer Network IP View



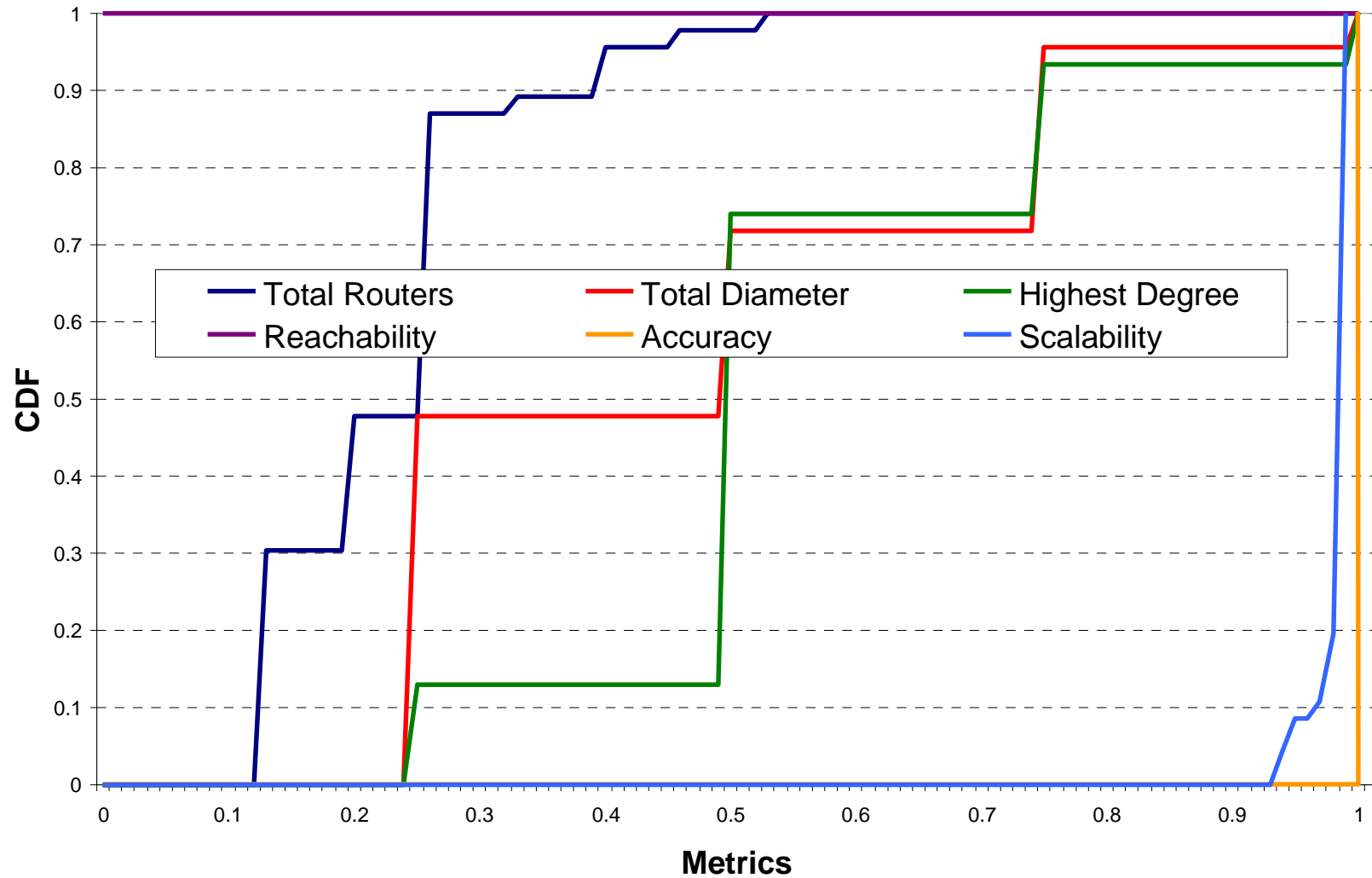
Accuracy Results for All Single Failures



Privacy Results for All Single Failures



Adding Scalability Results



Summary and Future Work

A general framework for reasoning and discussing cross-domain fault localization

Initial results demonstrating utility of the framework

Future Work:

- Validation of the generality for the approach
- Impacts of observation and model errors must be determined
- Privacy protection given a series of digests from the same domain
- Digest-sharing format and strategies must be explored

Thank you!

Questions?