Committing Conflicting Transactions in an STM

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Abstract
Dependence-aware transactional memory (DATM) is a recently proposed model for increasing concurrency of memory transactions without complicating their interface. DATM manages dependences between conflicting, uncommitted transactions so that they commit safely.

The contributions of this paper are twofold. First, we provide a safety proof for the dependence-aware model. This proof also shows that the DATM model accepts all concurrent interleavings that are conflict-serializable.

Second, we describe the first application of dependence tracking to software transactional memory (STM) design and implementation. We compare our implementation with a state of the art STM, TL2 [5]. We use benchmarks from the STAMP [22] suite, quantifying how dependence tracking converts certain types of transactional conflicts into successful commits. On high contention workloads, DATM is able to take advantage of dependences to speed up execution by up to 4.8×.

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1. Introduction
Interest in programming with transactions has experienced a renaissance with the advent of multi-core processors. Transactional memory [19], whether in software (STM) [31] or hardware (HTM) [16], replaces locks with transactions, promising an easier programming model without compromising performance.

Memory transactions provide atomicity: if a transaction fails for any reason its effects are discarded. Transactions provide isolation: no transaction sees the partial effects of any other. Transactions are also linearizable meaning that each committed transaction appears to take effect instantaneously at some point between when it starts and when it finishes.

A transactional conflict occurs when one transaction writes data that is read or written by another transaction. When the ordering of all conflicting memory accesses is identical to a serial execution order of all transactions, the execution is called conflict-serializable [8]. There are three kinds of memory conflicts, R→W, W→R, and W→W, where R is a read, W is a write, and R→W indicates that a memory location was first read by one transaction and subsequently written by another. Most transactional memory systems detect conflicts between pairs of transactions and respond by delaying or restarting one of the transactions. The key insight behind DATM is that this policy restricts concurrency more than is necessary [2]. DATM manages conflicts by making transactions aware of dependences and, in the case of a W→R dependence, forwards data values from one uncommitted transaction to another. Dependence-awareness allows two conflicting but conflict-serializable transactions to both commit safely, increasing concurrency and making better use of concurrent hardware [27].

This paper presents a formal model for dependence-aware transactions, proving them to be safe because transactions remain atomic and isolated. Moreover, the paper shows that the model allows every conflict-serializable schedule to occur.

The paper demonstrates the first application of dependence-awareness to STMs. Dependence-aware software transactional memory (DASTM) uses techniques from TL2 [5] that are modified to support dependences and data forwarding. We implement DASTM in C and in Java. The C version is word-based and the Java implementation is object-based. We evaluate DASTM on high contention workloads—a shared counter micro-benchmark, three programs from the STAMP benchmark suite [23], and STMBench7 [9]. We show that some STAMP benchmarks benefit from managing dependences and forwarding data between uncommitted transactions.

This paper makes the following contributions:
1. It presents a formal model for dependence-aware transactions and then proves its safety and its ability to accept any interleaving that is conflict-serializable.
2. It presents the design of a dependence-aware STM system, which we have implemented in both C and Java.
3. It presents performance data and statistics for our dependence-aware STM system. DASTM shows up to a 4.8× performance improvement on high contention benchmarks from
The system tracks all dependences at the level of memory bytes or objects. The dependences are tracked as they arise during transaction execution. R→W and W→R dependences restrict commit order, while W→R restrict commit order and forward data from the active transaction. When data is forwarded, the destination transaction must restart if the source restarts or overwrites the memory location whose value was previously forwarded.

Multiple dependences may arise if two transactions conflict on more than one memory cell. Dependences can form cycles among transactions, which must be broken by the system to avoid deadlock. Once detected, a cycle is resolved by restarting at least one transaction. A cyclic dependence means that the transactions have executed in a way that is not conflict serializable (this is formalized and proved in Section 3). The contention manager for dependence-aware transactions can break cycles using information from the dependence graph [27]. For example, it is probably advantageous to restart a transaction that has not forwarded any data, if possible.

2.4 Exceptions and stale data

Because the model forwards data between transactions, transactions that are doomed to restart (zombies) can read invalid or inconsistent data. Zombies will be restarted by the runtime when their source transaction either restarts or overwrites the incorrectly forwarded data. But before the zombie restarts, the runtime must contain the side effects of the zombie having read inconsistent data. The runtime effectively deals with zombie transactions by restarting them in a mode that prevents W→R dependences, thereby preventing them from reading forwarded data ("no-forward mode," details in Section 4.4).

2.5 Cascading aborts

Cascading aborts happen when one transaction’s abort causes other transactions to abort. In DATM, cascading aborts arise only from W→R dependences, where the source aborts or overwrites forwarded data. This data sharing pattern, with one transaction updating a variable multiple times while other transactions read it, is not conflict serializable. Any safe transactional system will serialize such transactions, either by stalling or aborting.

3. Formal model

This section introduces our formal model. For the first time, it proves that the DATM model is safe and that it accepts any conflict-serializable schedule.

3.1 Intuitions

Informally, one can think of a concurrency control mechanism as an automaton that accepts concurrent schedules of events. We prove two properties of DATM. First, DATM is an automaton that accepts only those schedules of transactions that preserve serializability.

Second, DATM accepts all conflict-serializable schedules. Contrast this with other TM systems that accept only a subset of the schedules because they either explicitly use two-phase locking or effectively have the same behavior as two-phase locking. We prove that all schedules are accepted by showing that DATM tracks read/write dependences and aborts transactions only if there are cycles in the underlying serialization graph.

The formal model is adapted from Lynch et al. [20]. The model uses non-deterministic transitions to avoid constraining implementations. For example, when a transaction reads a variable, it can read either that variable’s committed value or a value written by an uncommitted transaction.

3.2 Safety

A computation is modeled as a history, that is, a sequence of instantaneous events of the form:

- \( T, x.\text{read}(v) \): \( T \) reads \( v \) from variable \( x \).
- \( T, x.\text{write}(v) \): \( T \) writes \( v \) to variable \( x \).
- \( T\text{commit} \): \( T \) commits
• \((T \text{ abort})\): \(T\) aborts

For example, here is a history in which transaction \(T_A\) reads 0 from \(x\), writes 1 to \(y\), and commits.

\((T_A, x.\text{read}(0)) \cdot (T_A, y.\text{write}(1)) \cdot (T_A \text{ commit})\)

A history is well-formed if no transaction both commits and aborts, and if no transaction takes any steps after it commits or aborts. Without loss of generality, values read to and written from variables are unique.

A history is failure-free if all transactions commit, and it is serial if steps of distinct transactions are not interleaved. A serial failure-free history is legal if each value read from a variable is the value most recently written.

A subhistory of a history \(h\) is a sub-sequence of the events of \(h\). If \(h\) is a history and \(S\) is a set of transactions, \(h|S\) is the sub-sequence of events labeled with transactions in \(S\). Two histories, \(h\) and \(h'\), are equivalent if for every transaction \(T_A\), \(h|T_A = h'|T_A\). If \(h\) is a history, committed\((h)\) is the sub-sequence of \(h\) consisting of all events of committed transactions, and active\((h)\) is the set of active (not committed or aborted) transactions. If \(x\) is a variable, prior\((x, h)\) is the set of active transactions that have read or written \(x\) in \(h\), and value\((x, h)\) is the value written.

**Definition 3.1.** A history \(h\) is atomic if committed\((h)\) is equivalent to a legal failure-free serial history.

Let \(\text{serial}(h)\) be the serial history equivalent to committed\((h)\), in which transactions appear in the order of their commit events in \(h\).

A concurrency control mechanism can be thought of as an automaton that accepts concurrent histories. The mechanism is correct if those histories are atomic. We now define dependence-aware transactional memory as an automaton that accepts atomic histories. The automaton keeps the following state. The history accepted so far. For each transaction \(T\), the set of transactions that must commit before \(T\) can commit. We also keep track of notLater\((T)\), the set of transactions that must commit or abort before \(T\) can commit. Intuitively, earlier\((T)\) tracks the write-read dependence while notLater\((T)\) tracks all the remaining types of dependencies. Transitions are given by pre- and post-conditions, where \(X'\) denotes the new state of component \(X\).

An active transaction can always abort:

- Pre: \(T \in \text{active}(h)\)
- Post: \(h' = h \cdot (T \text{ abort})\)

This transition captures the effects of deadlock detection, either exact or inexact (that is, timeouts).

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- Premise: \(T \in \text{active}(h)\)
- Post: \(h' = h \cdot (T \cdot x.\text{read}(\text{value}(x, h)))\)
- \(\text{earlier}(T) = \text{earlier}(T) \cup \{\text{writer}(x, h)\}\)

When a transaction writes, we track its read-write and write-write dependences on the active transactions that read or wrote that variable.

- Premise: \(T \in \text{active}(h)\)
- Post: \(h' = h \cdot (T \cdot x.\text{write}(v))\)
- \(\text{notLater}(T) = \text{notLater}(T) \cup \text{prior}(x, h)\).

A transaction can commit only if every value it read was written by a now-committed transaction, and every value overwritten was previously read or written by a now-committed or now-aborted transaction.

- Premise: \(T \in \text{committed}(h)\)
- Post: \(h' = h \cdot (T \text{ commit})\)

The dependence-aware algorithm satisfies this simple invariant: for committed transactions, serialization does not reorder reads and writes to the same variable.

**Lemma 3.1.** Let \(w_0\) be a write event by \(T_0\), and \(e_1\) either a read or write event by \(T_1\), both to a variable \(x\) in \(h\). If \(w_0\) precedes \(e_1\) in serial\((h)\), then \(w_0\) precedes \(e_1\) in \(h\).

**Proof.** Suppose instead that \(e_1\) precedes \(w_0\) in \(h\). Because they were reordered, \(T_0\) and \(T_1\) were both active when \(w_0\) was appended to history \(h\). It follows that \(T_1 \in \text{prior}(x, h)\), so \(T_1 \in \text{notLater}(T_0)\), implying that \(T_1\) must commit before \(T_0\), ordering \(e_1\) before \(w_0\) in serial\((h)\), a contradiction.

**Lemma 3.2.** Let \(h\) be a history containing \(w_0\), a write event by \(T_0\), \(r_1\), a read event by \(T_1\) that returns the value written by \(w_0\), and \(w_2\), a write event by \(T_2\) that follows \(w_0\) in \(h\).

We claim that \(T_1 \in \text{notLater}(T_2)\).

**Proof.** Because \(r_1\) returns the value written by \(w_0\), there are no writes between \(w_0\) and \(r_1\). Therefore \(w_2\) follows \(r_1\) in \(h\), and the claim is established when \(w_2\) is appended to the history.

If \(r\) is a read event in \(h\), let readsFrom\((r, h')\) be the write event whose value \(r\) returns. That is, for every read event \(r\) in serial\((h)\),

\[
\text{readsFrom}(r, \text{serial}(h)) = \text{readsFrom}(r, h')
\]

(1)

The property holds vacuously in the original state. Suppose, by way of contradiction, the property becomes violated at some step. That step must be the commit of a transaction \(T_0\), because the other steps leave serial\((h)\) unchanged. Let \(r_0\) be a read step in \(h|T_0\) that violates the property, let \(w_1 = \text{readsFrom}(r, h')\), and let \(T_1\) be the transaction that executed \(w_1\).

First, \(w_1\) must be in serial\((h)\) because \(T_1 \in \text{earlier}(T_0)\), and a precondition for \(T_0\) to commit is that \(T_1\) be committed. Second, there can be no \(w_2\) by \(T_2\) between \(w_0\) and \(r_1\) in serial\((h)\). If \(w_2\) comes after \(w_1\) in serial\((h)\), then by Lemma 3.1, \(w_2\) comes after \(w_1\) in \(h\), so by Lemma 3.2, \(T_1 \in \text{notLater}(T_2)\), implying that \(T_1\) could not have committed after \(T_2\).

It follows that when a transaction commits, the new serial history is legal, because every read event returns the value written by the most recent write event in serial\((h')\).

### 3.3 Accepting all conflict-serializable histories

We have shown that our implementation is safe: all histories accepted are atomic. We now focus on a stronger claim, that this automaton accepts all conflict-serializable [8] histories. By contrast, most TM systems, whether hardware or software, accept only those histories admitted by two-phase locking, a strictly smaller set.

Some care is needed when interpreting this claim. As noted, an active transaction can be aborted at any time, for any reason. In practice, an implementation will abort a transaction only if it detects, or suspects, a deadlock resulting from a cyclic dependence.

Our automation accepts all conflict-serializable histories, but an actual implementation may reject some as a result of imprecise deadlock detection (for example, premature timeouts). Our implementation also turns off forwarding when it appears to be ineffective, for example, when restarting a transaction aborted by a cyclic dependence.

Any history has an associated serialization graph. Each node is labeled with a committed transaction, and there is a directed edge from \(T_0\) to \(T_1\), if first \(T_0\) and then \(T_1\) apply conflicting operations (at least one write) to the same object. A history is
conflict-serializable if and only if the associated serialization graph is acyclic \[8\].

We define a directed wait-graph for a history \( h \) as \( G(h) = (V, E) \) where \( V = \{ T : T \in \text{active}(h) \} \) and \( E = \{ (T_1, T_2) : T_1 \in \text{earlier}(T_2) \implies \text{notLater}(T_2) \land T_1, T_2 \in V \} \). Note that according to this wait-graph a transaction \( T \) commits iff it has no incoming edges.

To prove that the automaton accepts all conflict-serializable histories, we change the abort rule to reflect precise detection. A transaction is aborted if it has read a value from a transaction that later aborted or if it is part of a cycle in the wait-graph.

- **Pre:**
  - \( T \in \text{active}(h) \)
  - \( (\exists T_1 \in \text{earlier}(T) \land T_1 \in \text{aborted}(h)) \lor (T \in \text{cycle in } G(h)) \)
- **Post:** \( h' = h \cdot \langle T \text{ abort} \rangle \)

Observe that according to this new abort rule the first transaction abort will occur because of a cycle in the wait-graph. Subsequent aborts may occur due to the dependences tracked by the set \( \text{earlier}(T) \) or other cycles in the graph.

**Lemma 3.3.** If an input history \( H \) is conflict-serializable then \( G(H) \) is acyclic.

**Proof.** Let \( h \) be the earliest subhistory of \( H \) such that there is a cycle in \( G(h) \). Let \( \langle T_1, T_2, \ldots, T_k \rangle \) denote the cycle. Consider the nodes \( T_1 \) and \( T_k \). By definition the edge \( (T_k, T_1) \) exists because \( T_k \in \text{earlier}(T_1) \cup \text{notLater}(T_1) \). Using the transitive property, the chain of edges from \( T_1 \) to \( T_k \) imply that \( T_1 \in \text{earlier}(T_k) \cup \text{notLater}(T_k) \). Using the definitions of \( \text{earlier}(T) \) and \( \text{notLater}(T) \), there are 9 possible combinations of dependence between \( T_1 \) and \( T_k \). Each of these combinations result in a cycle between \( T_1 \) and \( T_k \) in the serializability graph of \( h \). This is a contradiction, because a cycle in the serializability graph of \( h \) implies \( H \) is not conflict-serializable.

**Lemma 3.4.** If an input history is conflict-serializable, then it is accepted by the automaton.

**Proof.** By Lemma 3.3, the wait-free graph for the input history is acyclic. According to the abort rule, no transaction would have aborted as the first abort is triggered by a cycle. Hence, the given history is accepted as-is by the automaton.

4. **Design**

This section introduces our prototype implementation of dependence-aware software transactional memory (DASTM). It presents the key data structures and the basic steps transactions follow. Finally, we discuss some of the more interesting optimizations.

### 4.1 Data structures

Each thread maintains transaction-specific information in thread-local storage. Each transaction has a read-set and a write-set, implemented as linked lists with bloom filters to reduce list searches (like TL2 \[5\]). There is a single shared global-clock vector. Each transaction also has a wait-vector to manage dependences.

The primary shared data structure is a global hashtable that contains the system metadata, shown in Figure 2. Active transactions hash memory addresses to look up memory metadata structures (MDs) in the hashtable. Each address requires a unique MD, so hashtable collisions are resolved using a linked list of entries. DASTM uses the same addressing interface as the STAMP TL2 implementation, where load and store addresses are 4-byte, aligned data units. Each MD contains the following fields.

- **lock**
- **ro-flag**
- **ro-version**
- **accessors**, a sequence of 4-tuples, each comprised of:
  - [transaction-id, flags, receivedValue, writtenValue]

For efficiency, all addresses that hash to the same value share the same lock ro-flag and ro-version. The lock is a recursive spinlock that protects access to the MD structure. The ro-flag and the ro-version enable an optimization for memory locations that are only read during a transaction (see Section 4.3.2).

The core of the MD structure is the accessors list, an ordered sequence of 4-tuples. Each tuple has a transaction-id that identifies the transaction accessing this memory location. The flags field contains four bits, Received, Written, Forwards, and Doomed. The first three bits indicate whether the tuple has received, written, or forwarded a value. The Doomed flag indicates that the transaction accessing the address will have to abort. The receivedValue field holds the memory value retrieved from memory or the forwarded value from another in-progress transaction. The writtenValue field records updates to the memory location made by the transaction.

### 4.2 Basic transaction execution

The following steps summarize transaction execution. Transactions end either in commit or abort (where aborted transactions restart).

1. **Transaction initialization.** Transactions begin by clearing the thread-local read and write sets. As described below, they obtain a transaction-id and initialize their wait-vector to all zeros.

2. **Transactional accesses.** Memory reads and writes add the address to the transaction’s thread-local read or write set (respectively). They then look up and create, if necessary, the MD structure corresponding to the memory address in the global hashtable. The lock protecting the MD structure is held for the duration of servicing the memory operation. If this access is the first access to the address by the transaction, a new 4-tuple is appended to the accessors sequence in the MD.

- **Reads.** If this is the first access to the memory location, the value is read either from an active transaction or from memory, and is then stored in the receivedValue field. Forwarding happens by having the transaction scan the accessors list backwards from the end for previous tuples. If it finds a tuple that does not have the Doomed flag set and has its Written flag set, the transaction copies the writtenValue, sets the Forwarded flag, and sets the received flag in the receiving transaction’s accessor tuple. If no such tuple exists, then the transaction initializes the receivedValue directly from the memory. The value returned for the read operation is the value in the receivedValue field, or, if the written flag is set, the value in the writtenValue field.
b **Writes.** The Written flag in the MD accessor flags field is turned on and the writtenValue field is updated with the new value being stored. If the memory address is previously read but not written (Written flag is not set), then it turns on the Doomed flag of all tuples that are later in the sequence.

3. **Transaction commit.**
   a **Resolve dependences.** Wait until all dependences are resolved, i.e., all transactions this one depends on \((\text{earlier}(T) \cup \text{notLater}(T))\) must commit or abort (see Section 4.3.3 for details).
   b **Write-set locking.** Acquire and hold the MD structure locks for all addresses in the write-set. If any write-set tuples for this transaction have the Doomed flag set, release all the locks and abort.
   c **Read-set validation.** Validate the read-set by ensuring that none of the MD accessor tuples for this transaction have the Doomed flag set. The MD structure is locked only for the duration of the check. If the validation fails, the transaction releases all held locks and aborts. The read set does not need to be locked for the duration of commit because any subsequent writer will form a dependence and wait for this transaction to commit.
   d **Write-back.** Write back the value of each element in the write-set to main memory, and release the MD lock. If the Forwarded flag of the transaction’s tuple is set, the transaction dooms any dependent transaction that has received a stale value for this memory address. The transaction scans the dependents, doing any entry that has its Received flag set if the receivedValue is different from the committing transaction’s writtenValue. This check terminates at the end of the sequence, or at a non-doomed tuple that does not have the Received flag set.

   The start of write-back is the transaction’s linearization point [17]—any transaction that starts write-back will successfully commit, with any contending transaction serializing afterwards.

4. **Transaction abort.** A transaction that aborts must ensure that all transactions dependent on it also abort. For all addresses in the write-set with the Forwarded flag set, the transaction sets the Doomed flag for all subsequent accesses by transactions that have the Received flag set. The transaction stops at the first non-doomed tuple that has the Written flag set and the Received flag clear. Each MD structure is locked only for the time it takes to perform this check.

5. **Cleanup.** Both Commit and Abort complete by removing all tuples that correspond to the transaction’s read and write set from the corresponding MD structures. The MD structures themselves (if dynamically allocated) may be freed if the tuple-sequence has become empty.

4.3 **Design details**

This section describes a few of the important optimizations and design choices made in our prototype.

4.3.1 **Resolving dependences**

A transaction must wait until all transactions on which it depends complete (commit or abort). After they commit, it can proceed (past step 3a) and continue its attempt to commit. A transaction’s dependences are implicitly encoded by its tuple’s position in the MD accessor sequence—the transactions of tuples preceding it in the sequence are the ones it may depend on. One strategy for resolving dependences is to iterate through each address in the working set, checking if all preceding transactions in the MD accessor list that have the Written flag set have completed. Recall that when a transaction completes, it removes its tuple from the MD accessor.

We implement a more efficient strategy for resolving dependences that uses vector clocks. The runtime has a *global-clock* \((GC)\) that can encode both a global clock and the number of transactions completed by each processor. Each transaction has a *wait-vector* \((V)\) that is used to summarize the transactions it has to wait on. When a transaction starts on a processor \(p\), it reads \(GC[p]\) (the \(p\)th entry in the vector clock) and keeps track of \(V = GC[p]+1\). This scalar \(V\) represents the value which the transaction will write into the *global-clock* when it completes, and is communicated to other processors that wish to take a dependence on this transaction. This communication occurs when a transaction accesses any memory address, it updates its *wait-vector* with the \(V\) values of all transactions preceding it in the accessor tuple. The \(V\) value is present in each tuple, as the transaction-id field encodes both \(p\) and \(V\). When a transaction completes (whether commit or abort), it writes \(V\) to \(GC[p]\), after dooming its write-set.

4.3.2 **Optimizing read data**

Most transactions read more data than they write. Some addresses are only read during a transaction and never written. For such transactions, the basic algorithm can impose a heavy performance penalty in the steps required to process a read (2a) and to validate the read-set at commit time (3c). For data that is only read during a transaction, we would like to avoid any MD structure locking, vector-clock management, tuple management, and so on.

Our approach initially assumes that all data accessed by a transaction is read-only—as indicated by the *ro-flag* field in the MD. The transaction reads the desired data from main memory, and saves the *ro-version* value in its read-set. The validation phase (3c) for such memory locations consists of ensuring that for each address the *ro-version* has not changed in the MD structure, and that the *ro-flag* still indicates that the address is in read-only mode.

If a transaction stores to a memory location (i.e. uses the MD structure), the *ro-flag* is cleared. Any transaction that previously read the location while the *ro-flag* was set will abort during validation if it sees that the flag has been turned off. With the flag off, reads are processed as in 2a. The runtime can decide to transition an MD back to read-only mode by resetting the *ro-flag* and increasing the *ro-version*. Increasing the *ro-version* ensures that any outstanding transaction that reads the location in read-only mode will abort during validation. The runtime might turn on all *ro-flags* if there are no active transactions, or might turn them on for every \(T\) transactions.

4.3.3 **Deadlock management**

Deadlock can arise in the commit protocol, steps 3a-c, for a variety of reasons. First, cyclical dependences in the DASTM model result in two transactions waiting for each other to commit, and thus both stay in step 3a indefinitely. Second, we do not impose any specific ordering on lock acquires (exacerbated by the fact that we acquire write-set locks before read-set), so transactions can deadlock in steps 3b or 3c. Third, since our implementation uses a single lock to protect multiple MD structures that hash to the same bucket, on rare occasions false conflicts can cause deadlocks.

Deadlocks are handled using timeout, similar to TL2. Other approaches are possible, including implementations that avoid deadlocks (e.g. by restricting dependence creation to guarantee acyclic dependences or imposing lock order), or which use more sophisticated deadlock detection techniques like Deadlocks [13].

4.3.4 **Design tradeoffs**

Our STM design does not implement every feature of the dependence-aware model. Transaction dependences are always created relative...
to the most recently written value of the object. With this policy, the dependence graph is always a chain, and new dependences are appended to the end. A given transaction will forward only a single value, even if the address is written multiple times. That single value can be forwarded to multiple transactions. Preliminary data indicated that these optimizations would generate little performance and add complexity.

4.4 Containing zombies

Because $W\rightarrow R$ dependences forward uncommitted data, a transaction can read invalid or inconsistent data (see Section 2.4). Zombie transactions (those that will never commit) can enter infinite loops, write to incorrect addresses, read from incorrect addresses, jump to incorrect addresses, and fail program assertions. Some STM systems allow zombie transactions and have mechanisms to deal with them [6]. DASTM’s control over data forwarding makes containing zombies easy.

With dependence-aware transactions, infinite loops are resolved by runtime support. When transaction A enters an infinite loop (that is not present in the original program), it must have read inconsistent data from a transaction B that will not successfully commit. When transaction B restarts, the runtime restarts transaction A. If B is also in an infinite loop because of a dependence on A, the runtime system periodically polls for circular dependences and restarts both transactions. In Java, the VM can propagate the restart. In C, the runtime system sends a signal.

The runtime buffers data written during a transaction, which prevents zombie transactions from corrupting the program’s data structures, and from causing spurious exceptions due to stores to incorrect addresses. Zombie transactions can load from incorrect or invalid addresses, causing incorrect control flow or spurious exceptions. When any transaction that has read forwarded data throws an exception, the transaction is restarted in no-forward mode. Otherwise, it will be restarted when the source of the inconsistent data restarts. A managed runtime can detect exceptions directly, while an unmanaged environment can use signal handlers.

Jumping to a loaded address in a transaction that has read forwarded data causes the runtime to restart the transaction in no-forward mode. Program assertions must be integrated with the STM runtime. Any failed assertion in a transaction that has read forwarded data is restarted in no-forward mode.

5. Evaluation

We conducted the experiments for DASTM on a Sun server using the UltraSparc T1 (Niagara) processor. This processor contains eight multi-threaded cores with four contexts per core, for a total of 32 total hardware contexts. The machine runs the 64-bit Linux 2.6.24-19 operating system. Our Java tests (DASTM-J) are on a machine with 4 quad-core Intel Xeon 2.93GHz processors, for a total of 16 hardware cores. The machine runs Linux kernel version 2.6.22-14. We use counter as a micro-benchmark to study how DASTM performs in the presence of hot-spots. We also report the performance results for three representative STAMP 0.9.8 benchmarks—vacation, labyrinth and ssc2a. We compare DASTM with unmodified TL2 [6] on each of these benchmarks. We report TL2 statistics that differ from those reported by Minh et al. [22] because their results are from a simulator, while ours are from real hardware. We use the TL2 code distributed with the STAMP suite. We ensure each benchmark’s threads are appropriately pinned to individual processors (using thread affinity) to avoid OS scheduling anomalies. We report the averages of three benchmark runs.

5.1 counter

Writing shared data within a transaction generally leads to hot-spots that result in poor performance of an STM. In Figure 3, we study the effect of updating a shared counter for a total of 100,000 times using a variable number of threads. Each increment transaction also contains a fixed amount of think time (5,000 iterations of a local loop), to simulate work on private data. TL2 does not scale at all, revealing the inherent lack of concurrency in two-phase locking systems. This micro-benchmark demonstrates how DASTM, in ideal conditions, can increase concurrency by allowing conflicting transactions to safely commit.

5.2 STAMP

vacation Vacation models a travel reservation system. It uses red-black trees to store data. Client tasks are performed within transactions to provide safe access to this data. Our experiments execute 1,000 transactions and use the parameters "-t 1000 -n 100 -u 50". This particular configuration has very high contention and more than 86% of the benchmark time is spent within transactions. Figure 4 depicts how DASTM compares to TL2. DASTM outperforms TL2 by 4.86× at 16 threads.

We see that vacation performance decreases on DASTM going from 16 to 32 threads. The abort rate doubles when going from 16 to 32 threads with almost all of vacation’s aborts due to timeouts waiting for dependences to be satisfied at commit (see Table 1 in Section 5.3 below). We increased the timeout value which decreased the abort rate and improved performance at 32 processor threads, nearly matching 16 thread performance. With more cores, deadlock detection that is more precise than simple timeouts (for
example, Dreadlocks [13]) are likely to become important to sustain good performance.

**labyrinth** The labyrinth benchmark uses Lee’s algorithm to find the shortest path between pairs of nodes in a maze [22]. The program reads and updates memory locations within data structures, such as a worklist and a grid. Most of the updates occur in long transactions. Figure 4 shows the results for a maze of size $256 \times 256 \times 5$, using parameters “-i random-x256-y256-z5-n256.txt”. The total number of transactions is between 514 to 576 (depending on the number of threads). With the default transaction boundaries, both TL2 and DASTM are able to scale well on this benchmark. We therefore decided to use different transaction boundaries: the benchmark’s primary loop creates two transactions per iteration, which we merge into a single transaction. This is another way to transactionalize the benchmark (producing the same results), however contention is much higher. Figure 5 shows the results for this variant, which we call labyrinth+. DASTM is able to improve performance by up to approximately 1.6× with additional cores, whereas TL2 is unable to improve beyond single thread performance. Neither system achieves any additional speedup as the number of hardware threads is increased above 2. Like vacation, aborts due to time out increase with more threads. In addition, overwrite aborts (shown as $A_2$ in Table 1) also increase with more threads. Experiments with increased timeout thresholds do reduce those aborts by up to 60%, but overwrite aborts remain unchanged and thus become the limiting factor for performance. Even with more sophisticated deadlock detection, labyrinth+ is inherently limited in the amount of concurrency that can automatically be achieved.

**ssca2** The ssca2 benchmark uses a scientific computational kernel that operates on a multi-graph to produce an efficient graph structure representation using adjacency (and other auxiliary) arrays [22]. We run the benchmark using the parameters “-s17 -i1.0 -u1.0 -l3 -p3”. It creates a large number of transactions: over 1.4 million, which individually are relatively small. The benchmark has very little contention, so it does not benefit much from dependence management. Figure 4 shows that on single-threaded runs, TL2 is roughly 20% faster than DASTM, due to overheads for managing metadata. Overheads for other benchmarks depend on a variety of factors including access to DASTM metadata, transaction contention, and the ratio of transaction computation to data accesses. TL2 achieves a peak speedup of approximately $2.4 \times$ at 32 threads, while DASTM’s overhead causes its peak speedup to be slightly lower at $2.25 \times$.

![Figure 4](image.png)

Figure 4. Speedup (higher is better) achieved by DASTM and TL2 compared to the single thread performance of TL2 on (A) vacation (B) labyrinth and (C) ssca2.

<table>
<thead>
<tr>
<th>Parameter (in %)</th>
<th>vacation</th>
<th>labyrinth+</th>
<th>counter</th>
</tr>
</thead>
<tbody>
<tr>
<td>Reduction in Exec-time</td>
<td>72.5</td>
<td>23.9</td>
<td>86.8</td>
</tr>
<tr>
<td>Reduction in Restarts</td>
<td>98.2</td>
<td>90.0</td>
<td>99.5</td>
</tr>
<tr>
<td>Abort Rate</td>
<td>44.3</td>
<td>88.8</td>
<td>3.3</td>
</tr>
<tr>
<td>$A_1$: Dep. Wait Aborts</td>
<td>79.5</td>
<td>62.6</td>
<td>20.7</td>
</tr>
<tr>
<td>$A_2$: Overwrite Aborts</td>
<td>16.2</td>
<td>34.0</td>
<td>79.3</td>
</tr>
<tr>
<td>$A_3$: Lock Timeout Aborts</td>
<td>4.2</td>
<td>0.0</td>
<td>0.0</td>
</tr>
<tr>
<td>$D_1$:Tx using R→W</td>
<td>3.6</td>
<td>3.8</td>
<td>0.0</td>
</tr>
<tr>
<td>$D_2$:Tx using W→W</td>
<td>1.3</td>
<td>76.6</td>
<td>99.6</td>
</tr>
<tr>
<td>$D_3$:Tx using W→R</td>
<td>34.0</td>
<td>77.4</td>
<td>99.6</td>
</tr>
</tbody>
</table>

Table 1. DASTM statistics for vacation, labyrinth+ and counter at 8 threads.

5.3 DASTM statistics

Table 1 shows the reduction in execution time and in transactional restarts moving from TL2 to DASTM at 8 threads for the three highest contention benchmarks—vacation, labyrinth+ and counter. We see that on all of them, the number of dynamic aborts is reduced by 90% or more. These findings validate our observation that current STMs abort more transactions than what is strictly necessary to remain safe. DASTM’s reduction in aborts translates to increased performance.

Table 1 also gives the percentage of transactions that restart (abort rate) and a breakdown of the various types of aborts and dependences seen in these benchmarks. The *Abort rate* of the vacation benchmark shows that 44.3% of the total transaction attempts resulted in aborts. These aborts occur for three reasons: (1) timeouts while waiting for dependences to be satisfied ($A_1$), (2) aborts because a transaction overwrote a value that it had already forwarded ($A_2$), and (3) timeouts while trying to acquire locks on memory locations ($A_3$). The values of categories $A_1$–$A_3$ equals 100% of aborts (nearly 100% for labyrinth+, which has some explicit calls to abort). In a workload such as the counter benchmark aborts are mostly due to forwarding of values that are then overwritten, while labyrinth+ and vacation mostly abort due to timeout while waiting for dependences to resolve.

$D_1$, $D_2$, and $D_3$ give the number of transactions involved in $R→W$, $W→W$ and $R→W$ dependences. For example, 99.6% of the transactions in counter read values forwarded by the $(W→R)$ dependences. The numbers in these categories do not total to 100% because a single transaction can have multiple dependence types.

5.4 DASTM-J: an object based STM

We have also implemented DASTM-J, an object based dependence-aware STM. DASTM-J is written in Java and uses the same high level design as presented in Section 4. We present the performance
of DASTM-J on STMBench7 to show that our prototype has scalable performance and that dependences are useful for large transactional workloads.

STMBench7 consists of traversals and modifications in a graph with a million objects [9]. The authors of STMBench7 note the difficulty that every public STM has in running their benchmark [7]. In Figure 6, we show the scalable performance of DASTM-J for two different inputs to STMBench7, creating a read-dominated and a read-write workload. At 16 threads, DASTM-J achieves more than 1,300 Tx/sec on the read-dominated workload. The read-dominated workload does not benefit from dependences, but 2.5% of transactions create dependences for the read-write workload. Dependences are more useful as contention increases.

6. Related work

In this section, we discuss the most relevant related work from the literature. There have been many recent advances in STM research [1, 10, 11, 15, 21]. We refer the reader to Larus and Rajwar for a comprehensive reference of transactional memory systems as of summer 2006 [19].

TM isolation Other transactional memory designs and implementations have also observed that modifying the safety conditions for transactions can allow a system to extract more concurrency from workloads. Along with DATM [26, 27], TSTM [2] identifies that using conflict serializability as a correctness criteria, rather than two-phase locking, benefits transactional memory systems by allowing more concurrency. However, their model is based on timestamp ordering, and does not accept every conflict serializable schedule (e.g., those that involve forwarding). The developers of CS-STM [30] (which utilizes a new consistency criterion that the authors call z-linearizable), also consider a variant of that algorithm which maintains full serializability. This variant (called S-STM) is only briefly described as using timestamps and vector clocks and having to maintains partial precedence graphs. The authors state that the runtime overhead of managing their intricate data structures can be prohibitive, especially for smaller transactions, though performance data is not reported.

SI-STM uses snapshot isolation, a weaker isolation level than conflict-serializability [29]. SI-STM shares some of the performance goals of DATM, trying to get conflicting transactions to commit. It also shares some implementation techniques with DATM, namely preserving multiple versions of the same memory byte. Snapshot isolation is more difficult for the programmer to reason about than conflict serializability and is applicable to fewer situations than DATM.

Database systems DATM can be viewed as an efficient implementation of a SGT-based (Serialization Graph Testing-based) certifying concurrency-control scheduler [3]. It is designed to permit recoverable schedules, a superset of ACA (Avoid Cascading Aborts) schedules. It does not build up the actual serialization graph, since the dependences on the shared objects provide sufficient information to provide the necessary constraints.

Transaction dependences also have roots in early database research. Spheres of control [4], in the context of a static hierarchy of abstract data types, introduced the notion of dynamic spheres created around actions accessing shared data. Transaction dependences are at one level a refinement and formalization of the general notion of spheres of control in a way that can be implemented in the context of transactional memory.

Time-domain addressing [28] (also called multi-version concurrency control (MVCC)) tracks multiple versions of objects modified concurrently, as does DATM, and thus both systems address similar issues. However, write-shared data are known to degrade MVCC performance, while DATM is designed to scale in their presence. Also, the techniques DATM employs to achieve conflict serializability (notably, the different types of dependences and the forwarding of uncommitted data) are not found in MVCC systems.

Changing the STM programming model TM systems can change the programming model to increase performance. The programmer must deal with more complexity, but the runtime can be more efficient.

Privatization [33], and its complement (publication) are programming technique that allows programmers to carefully manage when data is shared and accessible by other transactions, versus being private. They bridge the conceptual gap between per-CPU data structures and shared data structures. Early release [32] allows a programmer to drop transactional isolation on given memory locations. The programmer must be correct in his judgment that isolation is not needed on those locations, or the program will no longer be correct. Having code in an escape action access the same data as a paused transaction can cause semantic anomalies [24]. Open nesting [25] trades physical isolation for logical isolation, with the programmer guaranteeing correctness. All of these techniques require more programmer effort than DATM.

Galois classes [18] and transactional boosting [14] allow the programmer to provide inverse operations for the concurrent data structures. These techniques are orthogonal to dependence awareness, and can be used to complement them. They have the potential to eliminate structural conflicts in many situations, though programmers may have varying success providing inverses for different data structures (e.g., k-d tree inserts are not straightforward to handle), and defining commutativity relationships between all operations. Similarly, abstract nested transactions (ANTS) [12] attempt to reduce the performance effect of benign conflicts, but require the programmer identify the regions of code that are likely to be victims of such conflicts. The system then ensures that ANTs are re-executed appropriately if they do experience a conflict. ANTs differ from closed nesting in when the re-executing can occur, specifically ANT re-execution can be delayed until the top-level transaction attempts to commit.

7. Conclusion

Dependence-aware transactions allow conflicting transactions to safely commit. This paper presents a formal model of DATM, proves its key properties, and presents the design of the first STM implementation to use the model.
Experimental results from our prototypes (in C and Java) confirm the potential performance benefits of dependence-aware transactional memory as compared to traditional STM implementations.

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